

# VRL series ——

——— "Noiseless" and "Firm Body"

#### **Quiet operation**

Helical gear contribute to reduce vibration and noise.

#### Firm Body

Internal teeth are machined to the steel body directly to produce high output torque.

## Long Service Life

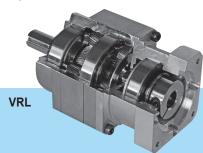
The high-class grease in ABLE reducer gives permanent lubrication. No need to replace the grease for the life time (20,000 hours).

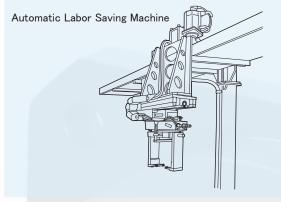
#### Easy mounting

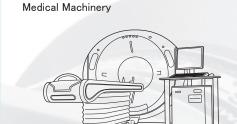
Motor can be mounted easily with adapter flange and bushing (without key). Applicable to each brand's servomotors.

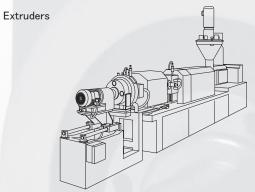
## **Variety of Ratios**

We can offer the fourteen ratios and anaible from 1/3 to 1/100.











**VRS** series

"Hight precision" and "Hight rigidity"

#### **Quiet operation**

Helical gear contribute to reduce vibration and noise.

# High precision

Standard backlash is 3 arc-min,ideal for precision control.

#### High rigidity

Employing taper roller bearing for the main output shaft to increase radial and axiol load.

# **Long Service Life**

The high-class grease in ABLE reducer gives permanent lubrication. No need to replace the grease for the life time (20,000 hours).

#### Easy mounting

Motor can be mounted easily with adapter flange and bushing (without key). Applicable to each brand's servomotors.



"Noiseless" and "Firm Body"

#### ■ Model Number Chart

ABLE reducer Servo Motor Best-In-Class Standard Backlash 5 arc-min K: Shaft with keyway Ratio: 1/3, 4, 5, 7, 10 (Single Reduction) 1/15, 20, 25, 30, 35, 40, 50, 70, 100 (Double Reduction) Frame Size: 050, 070, 090, 120 **VRLseries** Model Name for ABLE reducer Mount code varies depending on the motor

Adapter: The flange-shaped component for installing the servomotor to the gear reducer.

Bushing: In case the diameters of the output shaft of the servomotor and the input shaft of the gear reducer have different dimensions, this component can be inserted into the input shaft of the gear reducer as for the figure below. This makes the reducer's input shaft diameter to be equal to the output shaft of the servomotor.

Example: Mount code

## 19 HB 16

Output Shaft Diameter of the Servomotor

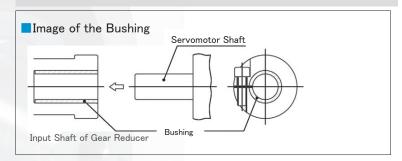
\*Adapter Code: Refer to the P.8 "Instruction of the Servo Reducer

Selection Tool" .:

XPlease consult us for other Adapter Code if necessary.

Bore Dimension of the Input Shaft of the Gear Reducer: 8, 14, 19, 28, 38, 45, & 65

Note: The  $\phi$  16 bushing needs to be inserted into the input shaft of the gear reducer for the above case.





#### ■VRL Series Specifications

Frame Size	Stages	Ratio	%1 Nominal Output	%2 Maximum Output	%3 Emergency Stop	%4 Nominal Input	※5 Maximum Input	%6 Permitted radial load	%7 Maximum radial load	%8 Permitted axial load	%9 Maximum axial load	%10 Permitted moment	※11 Weight
			Torque [Nm]	Torque [Nm]	Torque [Nm]	Speed [rpm]	Speed [rpm]	[N]	[N]	[N]	[N]	[Nm]	[kg]
		3	7	14	28	4000	8000	410		350			
	[	4	7.5	15	30	4000	8000	440		390			
	Single	5	7.5	15	30	4000	8000	470		420			0.9
		7	7.5	15	30	4000	8000	520		480			
		10	7 7	14 14	28	4000	8000	590		560			
		15 20	7.5	15	28 30	4000 4000	8000 8000	670 700		680 700			
050		25	7.5	15	30	4000	8000	700	700	700	700	34	
		30	7	14	28	4000	8000	700		700			
	Double	35	7.5	15	30	4000	8000	700		700			1.1
		40	7.5	15	30	4000	8000	700		700			
		50	7.5	15	30	4000	8000	700		700			
		70	7.5	15	30	4000	8000	700		700			
		100	7	14	28	4000	8000	700		700			
		3 4	20 25	40 50	80 100	3700 3700	6000	800 850		1000 1200			
	Single	5	25	50	100	3700	6000	910		1300			2.4
	O.I.Igio	7	25	50	100	3700	6000	1000		1500		117	
		10	20	40	80	3700	6000	1100		1700			
		15	20	40	80	3700	6000	1300		1700			
070		20	25	50	100	3700	6000	1400	1700	1700	1700		
""		25	25	50	100	3700	6000	1500		1700			
	D	30	20	40	80	3700	6000	1600		1700			0
	Double	35 40	25 25	50 50	100 100	3700 3700	6000 6000	1600 1700		1700 1700			3
		50	25	50	100	3700	6000	1700		1700			
		70	25	50	100	3700	6000	1700		1700			
		100	20	40	80	3700	6000	1700		1700			
		3	45	90	200	3400	6000	1000	1200				
		4	50	100	200	3400	6000	1100		1300			
	Single	5	50	100	200	3400	6000	1200		1500		277	4.7
		7 10	50 45	100 90	200 200	3400 3400	6000	1300 1500		1700 1900			
		15	45	90	200	3400	6000	1700		2400			
		20	50	100	200	3400	6000	1900		2600			
090		25	50	100	200	3400	6000	2000	3400	2900	3400		
	l l	30	45	90	200	3400	6000	2200		3100			
	Double	35	50	100	200	3400	6000	2200		3300			5.5
		40	50	100	200	3400	6000	2300		3400			
		50	50	100	200	3400	6000	2500		3400			
		70	50	100	200	3400	6000	2800		3400			
		100	45 101	90	200 480	3400 2600	4800	3100 1800		3400 2000			
		4	113	226	480	2600	4800	1900		2200			
	Single	5	113	226	480	2600	4800	2000		2400			8.9
		7	113	226	480	2600	4800	2200		2700			
		10	101	202	480	2600	4800	2500		3200			
		15	101	202	480	2600	4800	2900		3800			
120		20	113	226	480	2600	4800	3200	4800	4200	4800	490	
0		25	113	226	480	2600	4800	3400		4600	.500	.50	
	L	30	101	202	480	2600	4800	3700		4800			10
	Double	35 40	113 113	226 226	480 480	2600 2600	4800 4800	3800 3900		4800 4800			10
		50	113	226	480	2600	4800	4200		4800			
		70	113	226	480	2600	4800	4700		4800			
		100	101	202	480	2600	4800	4800		4800			

 $<sup>\</sup>frak{\%}1$  With nominal input speed, service life will be 20,000hours.

 $<sup>\</sup>frak{\%}2$  The maximum torque when starting and stopping.

 $<sup>\</sup>frak{3}$  The maximum torque when it receives shock (up to 1,000times)

<sup>%4</sup> The maximum average input speed.

<sup>%5</sup> The maximum momentary input speed.

<sup>%6</sup> With this load and nominal input speed, service life will be 20,000 hours.

<sup>%7</sup> The maximum value the reducer can accept.

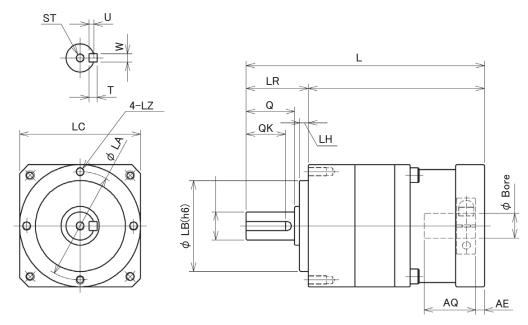
<sup>\*8</sup> With this load and nominal input speed, service life will be 20,000 hours.

X9 The maximum value the reducer can accept.

<sup>\*10</sup> The maximum value the reducer can accept.

<sup>\*\*11</sup> The weight may vary slightly model to model.

#### ■VRL Series Dimensions



Frame	Stages	Bore								Dimer	nsions												
Size	*1	%2	LA	LB	LC	LZ	LH	LR	LM ※3	L ※3	Q	S	ST	W	Т	U	QK	AE ※3	AQ %3				
	C: 1	≦8					4		78	102.5								5	27				
050	Single	≦14	44	35	50	M4		24.5	81	105.5	18	12	M4			2.5	13	5	30				
050	Double	≦8	44	35	50	Depth7			94	118.5	10	12	Depth7	4	4	2.5		5	27				
	Double	≦14							97	121.5								5	30				
	Single	≦14	62										95.5	131.5								5	30
070	Sirigie	≦19		52	70	M5 Depth10	5	36	107.5	143.5	28	16	M5 Depth10 5	5	5	3	22	7	43				
070	Double	≦8	02		/0				111	147								5	27				
	Double	≦14							114	150								5	30				
	Single	≦19							116.5	162.5								7	43				
090	Sirigie	≦28	80	68	90	M6	5	46	133.5	179.5	36	22	M8	6	6	3.5	28	12	55				
030	Double	≦14	00	00	30	Depth12	"	40	123.5	169.5	30	22	Depth13	U	U	0.0	20	5	30				
	Double	≦19							133.5	179.5								7	43				
	Single	≦28							145.5	215.5								12	55				
120	Olligie	≦38	108	90	120	M8	8	70	160.5	230.5	58	32	M12	10	8	5	45	15	67				
120	Double	≦19	100	30	120	Depth16	٥		148	218	50	32	Depth22	10		0	73	7	43				
	Double	≦28							165	235								12	55				

<sup>%1</sup> Single Reduction: Ratio  $1/3\sim1/10$ , Double reduction: Ratio  $1/15\sim1/100$ .

[ mm ]

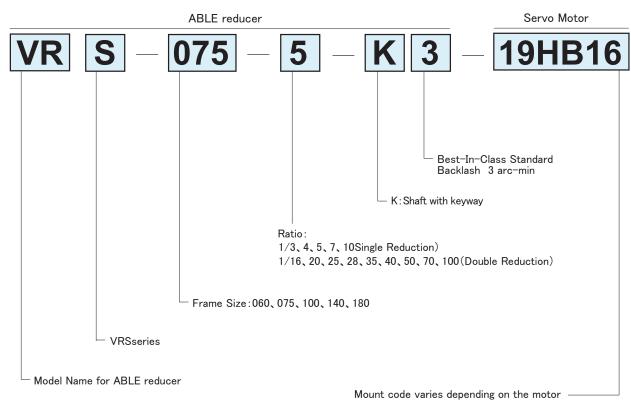
<sup>2</sup> Bushing will be inserted to adapt to motor shaft.3 Length will vary depending on motor adapter flange.



# MODEL NUMBER CHART Coaxial shaft VRS series

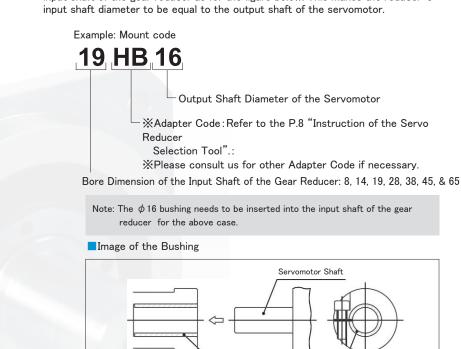
"Hight precision" and "Hight rigidity"

#### ■ Model Number Chart



Adapter: The flange-shaped component for installing the servomotor to the gear reducer.

Bushing: In case the diameters of the output shaft of the servomotor and the input shaft of the gear reducer have different dimensions, this component can be inserted into the input shaft of the gear reducer as for the figure below. This makes the reducer's input shaft diameter to be equal to the output shaft of the servomotor.



Input Shaft of Gear Reducer

Bushing

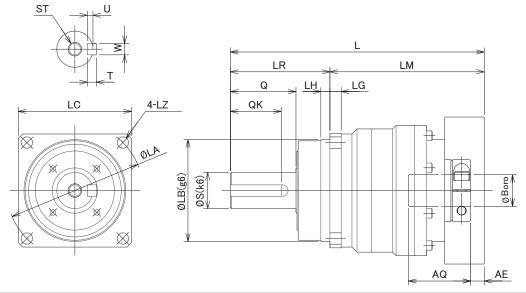
## ■VRL Series Specifications

			<b>※</b> 1	<b>※</b> 2	<b>*</b> 3	<b>※</b> 4	<b>※</b> 5	<b>%</b> 6	<b>※</b> 7	<b>%</b> 8	<b>※</b> 9	<b>※10</b>	<b>※</b> 1
Frame		D. C.	Nominal	Maximum	Emergency	Nominal	Maximum	Permitted	Maximum	Permitted	Maximum	Permitted	Weig
Size	Stages	Ratio	Output Torque	Output Torque	Stop Torque	Input	Input Speed	radial load	radial load	axial load	axial load	moment	
			[Nm]	[Nm]	[Nm]	Speed[rpm]	[rpm]	[N]	[N]	[N]	[N]	[Nm]	[kg
		3	17	36	80	3300	6000	1600		2100			
		4	26	40	100	3300	6000	1700		2200			١.,
	Single	5 7	26 26	40 40	100 100	3300 4000	6000	1900 1900		2400 2500			1.
		10	26	36	80	4000	6000 6000	2200		2500			
		16	26	40	100	4400	6000	2500		2500			
000		20	26	40	100	4400	6000	2600	2800	2500	0500	150	
060		25	26	40	100	4400	6000	2800	2800	2500	2500	152	
		28	26	40	100	4400	6000	2800		2500			
	Double	35	26	40	100	4400	6000	2800		2500			2
		40 50	26 26	40 40	100 100	4400 4800	6000 6000	2800 2800		2500 2500			
		70	26	40	100	5500	6000	2800		2500			
		100	26	36	80	5500	6000	2800	1	2500			
		3	47	90	200	2900	6000	2200		3200			
		4	75	125	250	2900	6000	2400		3400			
	Single	5	75	125	250	2900	6000	2500		3400			3
		7 10	75	125	250	3100	6000	2700	-	3400		265	
		16	75 75	90 125	200 250	3100 3500	6000 6000	3000 3400		3400 3400			-
		20	75	125	250	3500	6000	3700		3400			
075		25	75	125	250	3500	6000	3900	4200	3400	3400		
		28	75	125	250	3500	6000	4000		3400			
	Double	35	75	125	250	3500	6000	4200		3400			4
		40	75	125	250	3500	6000	4200		3400			
		50 70	75 75	125 125	250 250	3800 4500	6000 6000	4200 4200		3400 3400			
		100	75	90	200	4500	6000	4200		3400			
		3	120	240	500	2500	4500	3500		4600			_
5		4	180	320	625	2500	4500	3700		4900			
	Single	5	180	320	625	2500	4500	3900		5000			7
		7	180	320	625	2800	4500	4200		5400			
		10 16	180	240	500	2800	4500	4700		5800 5800			$\vdash$
		20	180 180	320 320	625 625	3100 3100	4500 4500	5300 5700	5000				
100		25	180	320	625	3100	4500	6100	6500	5800	5800	530	
		28	180	320	625	3100	4500	6300		5800			
	Double	35	180	320	625	3100	4500	6500		5800			
		40	180	320	625	3100	4500	6500		5800			
		50	180	320	625	3500	4500	6500		5800	-		
		70 100	180 180	320 240	625 500	4200 4200	4500 4500	6500 6500		5800 5800			
		3	200	500	1000	2100	4000	7500		10000			+
		4	360	650	1250	2100	4000	8100		10000			
	Single	5	360	650	1250	2100	4000	8600		10000			1
		7	360	650	1250	2600	4000	8900		10000			
		10	360	500	1000	2600	4000	9900		10000			
		16 20	360 360	650 650	1250 1250	2900 2900	4000 4000	10000		10000			
140		25	360	650	1250	2900	4000	10000 10000	10000	10000 10000	10000	1100	
		28	360	650	1250	2900	4000	10000		10000			
	Double	35	360	650	1250	2900	4000	10000		10000			:
		40	360	650	1250	2900	4000	10000		10000			
		50	360	650	1250	3200	4000	10000		10000			
		70	360	650	1250	3200	4000	10000		10000			
		100 3	360 530	500 1000	1000 2200	3900 1500	4000 3500	10000 14000		10000 15000			-
		4	750	1400	2750	1500	3500	15000		15000			
	Single	5	750	1400	2750	1500	3500	15000		15000			
		7	750	1400	2750	2300	3500	15000		15000			
		10	750	1000	2200	2300	3500	15000		15000			
		16	750	1400	2750	2700	4000	15000		15000			
180		20	750	1400	2750	2700	4000	15000	15000	15000	15000	1910	
		25	750 750	1400 1400	2750	2700	4000	15000		15000			
	Double	28 35	750 750	1400	2750 2750	2700 2700	4000 4000	15000 15000		15000 15000			١.
	Bouble	40	750	1400	2750	2700	4000	15000		15000			1
		50	750	1400	2750	2900	4000	15000		15000			
		70	750	1400	2750	3200	4000	15000		15000			1
	100	750	1000	2200	3400	4000	15000		15000				

<sup>X1 With nominal input speed, service life will be 20,000hours.
X2 The maximum torque when starting and stopping.
X3 The maximum torque when it receives shock (up to 1,000times)
X4 The maximum average input speed.
X5 The maximum momentary input speed.
X6 With this load and nominal input speed, service life will be 20,000 hours.</sup> 

<sup>\$\</sup>infty 1\$ The maximum value the reducer can accept.
\$\infty 8\$ With this load and nominal input speed, service life will be 20,000 hours.
\$\infty 9\$ The maximum value the reducer can accept.
\$\infty 10\$ The maximum value the reducer can accept.
\$\infty 11\$ The weight may vary slightly model to model.

#### ■VRS Series Dimensions



Fram	Stages	Bore									Dimer	nsions								
Size	<b>※</b> 1	<b>※</b> 2	LA	LB	LC	LZ	LG	LH	LR	LM	L	Q	S	ST	W	Т	U	QK	AE <sup>**3</sup>	AQ <sup>**3</sup>
		≦8						5	48	85.5	133.5								5	27
	Single	≦14	1							89	137			M5					5	30
060		≦19	68	60	60	5.5	6			105.5	153.5	28	16	Depth	5	5	3	22	7	43
	D 11	≦8								110	158			12.5					5	27
	Double	≦14								113.5	161.5								5	30
		≦14							56	103	159			M8 Depth 19					5	30
	Single	≦19								113	169		22 [		6	6	3.5	28	7	43
075		≦28	85	70	75	7.5	7	6		130	186	36							12	55
0/3		≦8	00	/0	/5	7.5	<i>'</i>			122.5	178.5	30							5	27
	Double	≦14								131	187			13					5	30
		≦19								141	197								7	43
		≦19	28 38 14 19							122	210								7	43
	Single	≦28						8	88	136.5	224.5	58		M10					12	55
100		≦38		90	100	10	10			151.5	239.5		32	M12 Depth	10	8	5	45	15	67
100		≦14			100		10			141	229		32	28	10			45	5	30
	Double	≦19								151	239								7	43
		≦28								168	256								12	55
		≦28								157	269								12	55
	Single	≦38					12	10	112	172	284			M16			5		15	67
140		≦48	165	130	140	11				188	300	82	40	Depth	12	8		65	10	88
140		≦19	100	100	140	''				174.5	286.5		40	36	12	0		00	7	43
	Double									189.5	301.5			00					12	55
		≦38								207	319								15	67
		≦38								203	315								15	67
	Single	≦48								219	331			M20					10	88
180		≦65	215	160	180	13.5	15	12	112	263	375	82	55	Depth	16	10	6	63	20	102
100		≦28	213		130	13.5	'3			228	340			42	10	10	0	03	12	55
	Double									244	356								15	67
		≦48								268	380								10	88

<sup>%1</sup> Single Reduction: Ratio 1/3~1/10, Double reduction: Ratio 1/15~1/100.

[ mm ]

<sup>%2</sup> Bushing will be inserted to adapt to motor shaft.

 $<sup>\</sup>ensuremath{\%3}$  Length will vary depending on motor adapter flange.

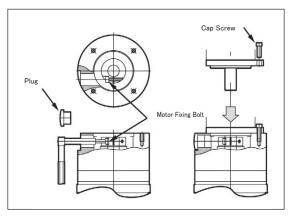
# Coaxial shaft VRL/VRS series

# **Servo Motor Assembly Installation**

Reducers can be fixed to servo motors quite easily. Everybody can do it for himself.

#### 1 Servo Motor Assembly Installation

- \* Wipe out the anticorrosive oil on the Motor shaft.
- (1)Remove the Rubber Cap and turn the Input Shaft until the Cap Screw is seen. Make sure the set bolt is loosened.
- (2)Carefully insert Servo Motor Shaft into the Input Shaft . (It should be inserted smoothly.) Make sure to insert motor straight. Please confirm the surface of the flanges of the motor and the reducer are fixed with no clearance.
- (3)Install the Servo Motor to the reducer and tighten the Motor Fixing Bolts to the proper torque. Refer to the table below.
- (4) Tighten the Cap Screw of the Input Shaft with a Torque Wrench to the proper torque. Refer to the table below.
- (5)Reinstall the rubber cap.



#### [Bolt tightening torque]

D-# C:	Motor Fi	xing Bolt	Screw Bolt				
Bolt Size	Nm	kgfm	Nm	kgfm			
М3	1.0	0.10	1.8	0.18			
M4	2.3	0.23	4.3	0.44			
M5	4.7	0.48	8.7	0.89			
M6	8.0	0.82	15	1.5			
M8	19	1.9	36	3.7			
M10	38	3.9	72	7.3			
M12	67	6.8	125	12.8			

#### 2 Installation of Reducer

- (1)In case you attach the servo motor by yourself, please be aware of cautions below.
- (2)Please make sure to fit the servo motor that was specified when ordering. Other motor model may be unacceptable because the input flange of the ABLE reducer is made for a particular motor.
- (3)The output shaft of the servo motor can be covered by anticorrsive oil.

#### [Bolt tightening torque for reducer]

Bolt Size	Motor Fixing Bolt							
Boit Size	Nm	kgfm						
M5	6.3	0.63						
M6	11	1.1						
M8	26	2.7						
M10	51	5.2						
M12	89	9.1						